

# Time series

SEM 2 2020

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The screenshot shows a mobile application interface with a status bar at the top displaying the time 14:50 and various system icons. Below the status bar, there are four sections, each with a title and a horizontal Likert scale from 0 to 4. The scales are as follows:

- Thoughts of ending your life:** Scale 0-4, with '0' selected.
- Crying easily:** Scale 0-4, with '2' selected.
- Feelings of being trapped or caught:** Scale 0-4, with '1' selected.
- Blaming yourself for things:** Scale 0-4, with '0' selected.

At the bottom of the screen, there is a navigation bar with three icons: a menu icon, a settings gear icon, and an information 'i' icon.

- ▶ One person measured several times in a short period
- ▶ Cases can **not** reasonably be assumed to be *independent*
  - ▶ Knowing someone's level of fatigue at a time point helps predict his or her level of fatigue at the next time point.
- ▶ Likelihood not easy to compute without two assumptions:
  - ▶ The time-series factorize according to a graph
  - ▶ The model does not change over time

lag-0

$$Y_1^{(p)}$$

$$Y_2^{(p)}$$

$$Y_3^{(p)}$$

$$Y_4^{(p)}$$

$$Y_5^{(p)}$$

lag-1

$$Y_1^{(p)}$$

$$Y_2^{(p)}$$

$$Y_3^{(p)}$$

$$Y_4^{(p)}$$

$$Y_5^{(p)}$$

lag-2

$$Y_1^{(p)}$$

$$Y_2^{(p)}$$

$$Y_3^{(p)}$$

$$Y_4^{(p)}$$

$$Y_5^{(p)}$$

Suppose the first five measurements of a time-series dataset with three variables are:

$$\mathbf{Y} = \begin{array}{c} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{array} \begin{array}{ccc} y_1 & y_2 & y_3 \\ \left[ \begin{array}{ccc} 6 & 6 & 7 \\ 5 & 5 & 5 \\ 5 & 5 & 2 \\ 2 & 2 & 2 \\ 1 & 1 & 3 \end{array} \right] \end{array}$$

Suppose the first five measurements of a time-series dataset with three variables are:

$$\mathbf{Y} = \begin{matrix} & y_1 & y_2 & y_3 \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} & \left[ \begin{array}{ccc} 6 & 6 & 7 \\ 5 & 5 & 5 \\ 5 & 5 & 2 \\ 2 & 2 & 2 \\ 1 & 1 & 3 \end{array} \right] \end{matrix}$$

If we want to properly model the likelihood, we need to take into account that *all* cases are correlated. This can be done by modeling  $\text{vec}(\mathbf{Y}^T)$ , of which we have one case:

$$\text{vec}(\mathbf{Y}^T)^T = \left[ \begin{array}{cccccccccccccccc} y_{11} & y_{12} & y_{13} & y_{21} & y_{22} & y_{23} & y_{31} & y_{32} & y_{33} & y_{41} & y_{42} & y_{43} & y_{51} & y_{52} & y_{53} \\ 6 & 6 & 7 & 5 & 5 & 5 & 5 & 5 & 2 & 2 & 2 & 2 & 1 & 1 & 3 \end{array} \right]$$

Suppose the first five measurements of a time-series dataset with three variables are:

$$\mathbf{Y} = \begin{matrix} & & y_1 & y_2 & y_3 \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} & \left[ \begin{array}{ccc} 6 & 6 & 7 \\ 5 & 5 & 5 \\ 5 & 5 & 2 \\ 2 & 2 & 2 \\ 1 & 1 & 3 \end{array} \right] \end{matrix}$$

If we want to properly model the likelihood, we need to take into account that *all* cases are correlated. This can be done by modeling  $\text{vec}(\mathbf{Y}^\top)$ , of which we have one case:

$$\text{vec}(\mathbf{Y}^\top)^\top = \left[ \begin{array}{cccccccccccccccc} y_{11} & y_{12} & y_{13} & y_{21} & y_{22} & y_{23} & y_{31} & y_{32} & y_{33} & y_{41} & y_{42} & y_{43} & y_{51} & y_{52} & y_{53} \\ 6 & 6 & 7 & 5 & 5 & 5 & 5 & 5 & 2 & 2 & 2 & 2 & 1 & 1 & 3 \end{array} \right]$$

The variance-covariance structure of this vector then is highly structured, and should include all implied covariances (lag-1, lag-2, lag-3...). Computing such a model is typically too complex!

Trick: rather than modeling  $\mathbf{y}_t$ , model the vector  $\mathbf{z}^\top = [\mathbf{y}_{t-1} \ \mathbf{y}_t]$ , and treat these as independent cases:

$$\mathbf{Z} = \begin{matrix} & & y_{t-1,1} & y_{t-1,2} & y_{t-1,3} & y_{t,1} & y_{t,2} & y_{t,3} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} & \left[ \begin{array}{cccccc} \cdot & \cdot & \cdot & 6 & 6 & 7 \\ 6 & 6 & 7 & 5 & 5 & 5 \\ 5 & 5 & 5 & 5 & 5 & 2 \\ 5 & 5 & 2 & 2 & 2 & 2 \\ 2 & 2 & 2 & 1 & 1 & 3 \end{array} \right] \end{matrix}$$

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The variance–covariance structure then is a *Toeplitz matrix*:

$$\Sigma = \begin{bmatrix} \Sigma_{t-1,t-1} & \Sigma_{t-1,t} \\ \Sigma_{t,t-1} & \Sigma_{t,t} \end{bmatrix}$$

Which is typically used to fit SEM models. Two downsides of this method:

- ▶ Not the *true* likelihood
- ▶ Lag factorization now is assumption, not tested!



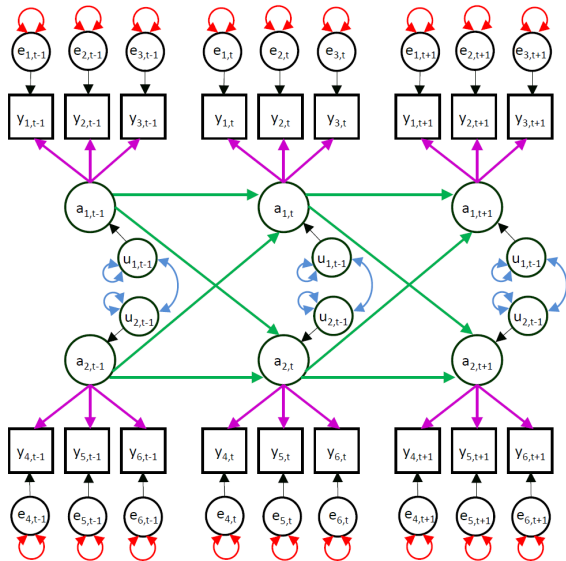
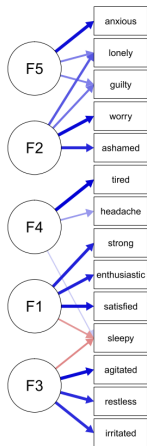
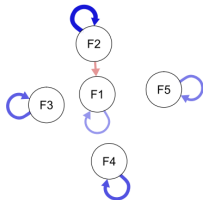


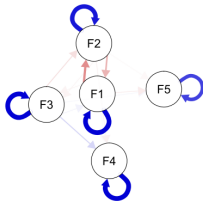
Figure by Ellen Hamaker



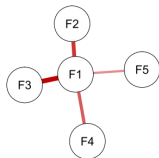
**(a)** Estimated factor loadings.



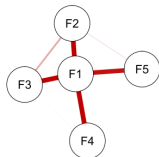
**(b)** Estimated temporal network, standardized to partial directed correlations.



**(c)** Case-drop bootstrap (25%) inclusion proportions of edges in the temporal network.



**(d)** Estimated contemporaneous network, standardized to partial correlations.



**(e)** Case-drop bootstrap (25%) inclusion proportions of edges in the contemporaneous network.